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Mathematics of Signal Processing: A First Course Charles L. Byrne Department of Mathematical Sciences University of Massachusetts Lowell Lowell, MA 01854

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Chapter 4 focuses on FIR filters and its purpose is to introduce two basic signal processing methods: block-by-block processing and sample-by-sample processing. In the block processing part, we discuss convolution and several ways of thinking about it, transient and steady-state behavior, and real-time processing on a block-by-block basis using the overlap-add method and its software implementation.

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