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Abstract: This paper deals with the control of lighter-than-air vehicles, more specifically the design of an integrated guidance, navigation and control (GNC) scheme that is capable of navigating an airship through a series of constant-altitude, planar waypoints. Two guidance schemes are

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A Lighter Than Air Robot (LTAR) is an unmanned lighter than air vehicle with sufficient autonomy. Robotic airships can also be called Aerobot.

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